

# Channel Model in Magnetic Recording Channel (MRC)

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**Description:** Simulate the error pattern in the Longitude Magnetic Recording Channel

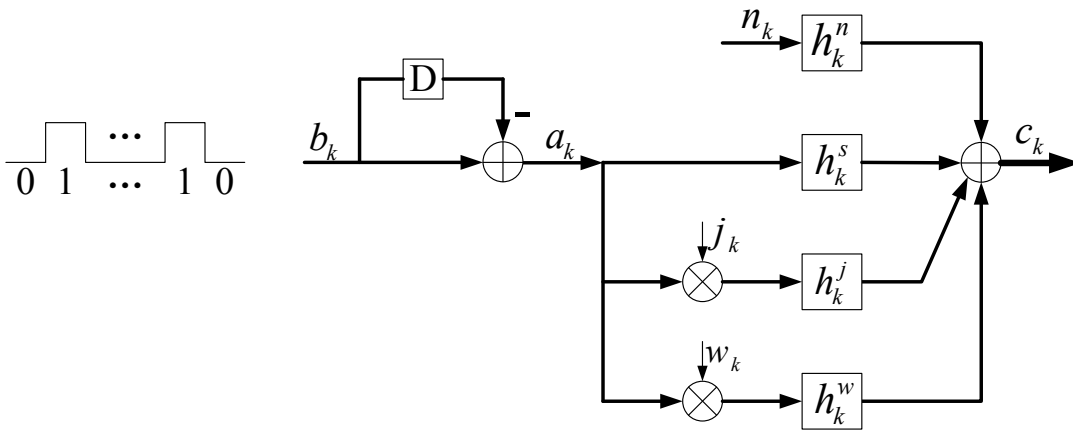


Figure 1: Discrete Channel Model for MRC

- **Detailed Description**

As shown in Figure ??, the data bits vector  $b_k$  sequentially passed the channel model so that we could get the simulated readback data vector  $c_k$ . The error pattern mainly is generated from 4 parts, the transition response  $h_k^s$ , the first-order position jitter response  $h_k^j$ , the first-order width jitter response  $h_k^w$  and the white noise response  $h_k^n$ . These four different responses are all in discrete form, which means that each response is discretized into corresponding vectors. In a word, by adding some sequences into the original data vector  $b_k$ , we could get the discretized readback signal  $c_k$ .

Given the parameters SNRdB, recording density  $D_s$ , fraction of noise power due to media noise  $\alpha$ , percentage of media noise power due to width variation  $\lambda$ , and the power of the transition  $E_t$ , we could get the variance of the white noise  $\alpha_n$ , the variance of position jitter noise  $\alpha_j$ , the variance of width variation  $\alpha_w$  and also series of the corresponding response  $h_k^n$ ,  $h_k^j$ ,  $h_k^w$  and series of the transition response  $h_k^s$ . The following is the detailed equations.

$$N_\alpha = E_t 10^{-SNRdB/10} \quad (1)$$

$$N_0 = (1 - \alpha)N_\alpha \quad M = \alpha N_\alpha \quad (2)$$

$$M_j = (1 - \lambda)M \quad M_w = \lambda M \quad (3)$$

$$\alpha_n = \sqrt{\frac{N_0}{2}} \quad \alpha_j = \sqrt{\frac{M_j}{4E_t}} \quad \alpha_w = \sqrt{\frac{M_w}{4E_t}} \quad (4)$$

$$h_k^s = E_t \frac{D_s^2}{D_s^2 + k^2} \quad (5)$$

$$h_k^j = -E_t \frac{2D_s^3 k}{(D_s^2 + k^2)^2} \quad (6)$$

$$h_k^w = -E_t D_s^2 \frac{D_s^2 - k^2}{(D_s^2 + k^2)^2} \quad (7)$$

$$h_k^n = \sqrt{\frac{E_t D_s}{2\pi}} \tanh\left(\frac{D_s \pi}{2}\right) \frac{k + \frac{D_s}{2}}{(\frac{D_s}{2})^2 + k^2} \quad (8)$$

And usually,  $E_t$  is normalized to 1.

- **Specified**

The sequences of the white noise, position jitter and width jitter are normally distributed pseudorandom sequences, which could be generated using gsl (<http://www.gnu.org/software/gsl/>).