



EXPONENTIAL PATTERN RETRIEVAL CAPACITY WITH NON-BINARY ASSOCIATIVE MEMORY

Joint work with: Raj K. Kumar Amin Shokrollahi

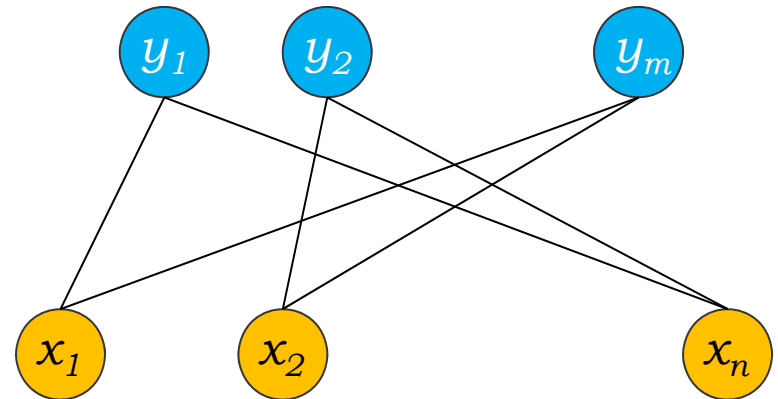
Amir Hesam Salavati

IN THIS TALK...

- ◎ The problem
- ◎ Our proposed solution
 - Intuition
 - Details
 - Results
- ◎ Work in progress
- ◎ Conclusions and final remarks

THE PROBLEM IN A NUTSHELL

- ⊙ For a coding theorist:
 - ⊙ Given: A *parity check graph*.
 - ⊙ Required: A "*simple*" message passing decoding algorithm with restrictions on decoding nodes.

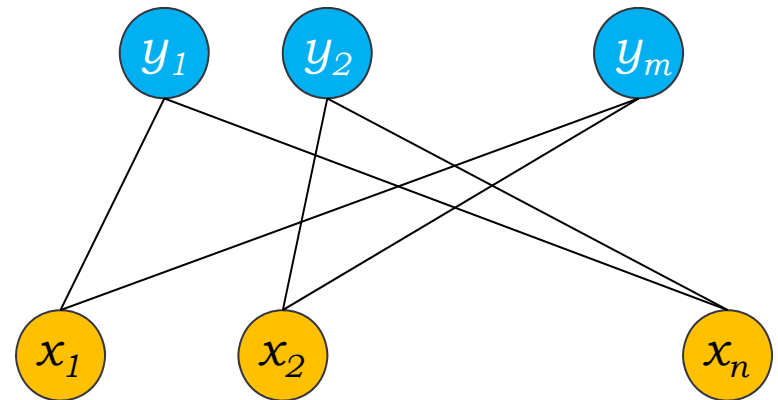


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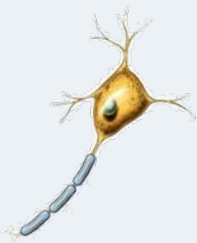
⊙ Required: A "*simple*" message passing decoding algorithm with restrictions on decoding nodes.



⊙ For a neuroscientist:

⊙ Given: A *hetero-associative* neural network.

⊙ Required: A method to increase the storage capacity.



WHY IS IT INTERESTING?

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- Hopfield, 1982
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- ⊙ For the past three decades, best neural realizations yield pattern retrieval capacities linear in n .
- ⊙ For similar structures, we have exponential “pattern retrieval” capacities in coding theory.

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SOLUTION IDEA

Introduction

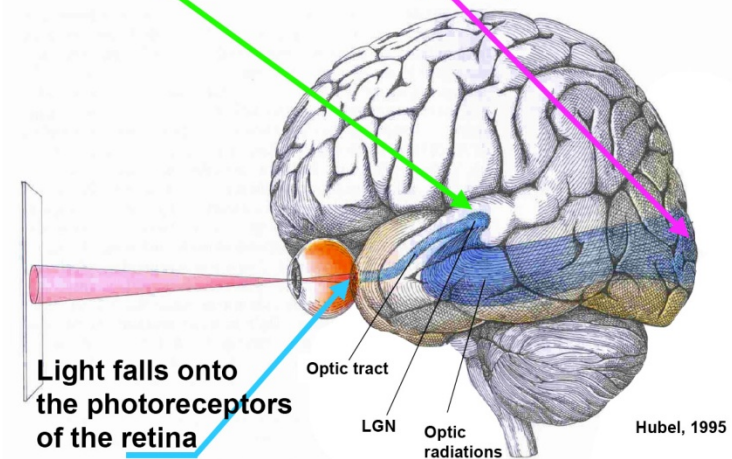


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- ⊙ What if we only focus on memorizing structured patterns?
 - ⊙ Better distant properties.
- ⊙ Successful recent attempts to increasing storage capacities using *structured* patterns.
- ⊙ It seems biologically relevant as well.

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Thalamus (LGN) serves strategic role in gating of information flow to cortex



OUR SUGGESTED SOLUTION

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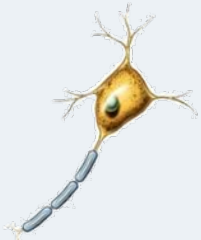


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 - ⊙ An algorithm with simple decoding nodes.
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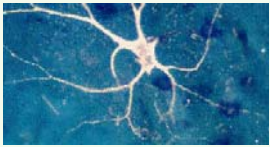


- ⊙ Rephrased in neuroscience parlance:
 - ⊙ Only store patterns that satisfy some constraints.
 - ⊙ Constraints from pre-processing stages in brain or outside world.
 - ⊙ Constraints will help in dealing with noise.



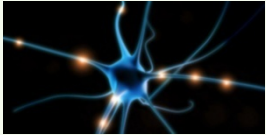
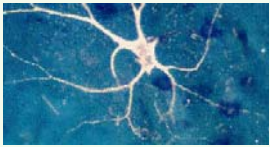
MODEL AND METHOD

NEURAL NETWORKS



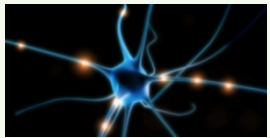
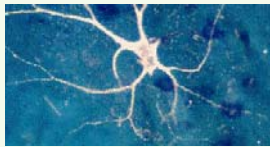
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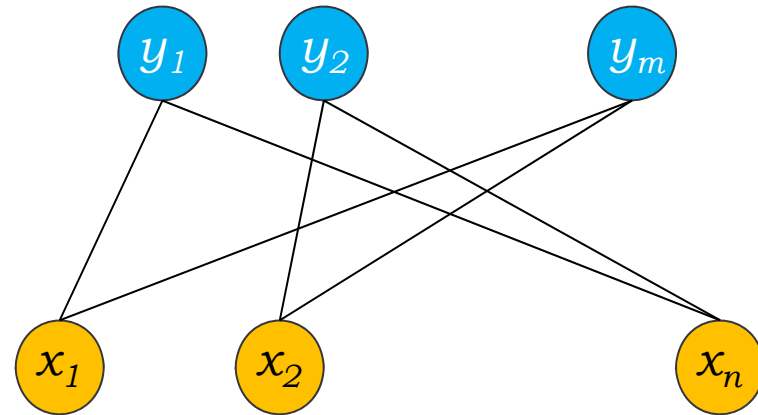
NEURAL NETWORKS



- ◎ **Neuron**: a basic processor in the nervous system.
- ◎ Neurons communicate via **spikes**.
- ◎ Neurons can:
 - ◎ Compute a linear sum (count the spikes they receive).
 - ◎ Transmit a **spike train** based on this sum.
 - ◎ What they transmit goes to all their neighbors (**broadcast** system).

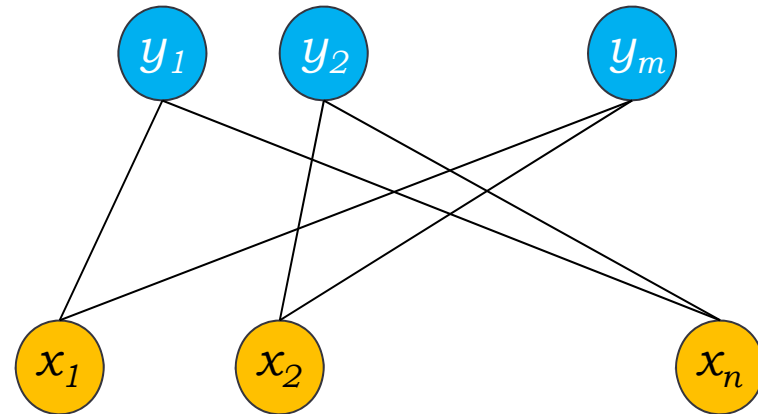
MODEL

- ⊙ A bipartite graph with n pattern nodes and m constraint nodes.
- ⊙ Nodes represent neurons.
- ⊙ Link weights are 0 or 1.



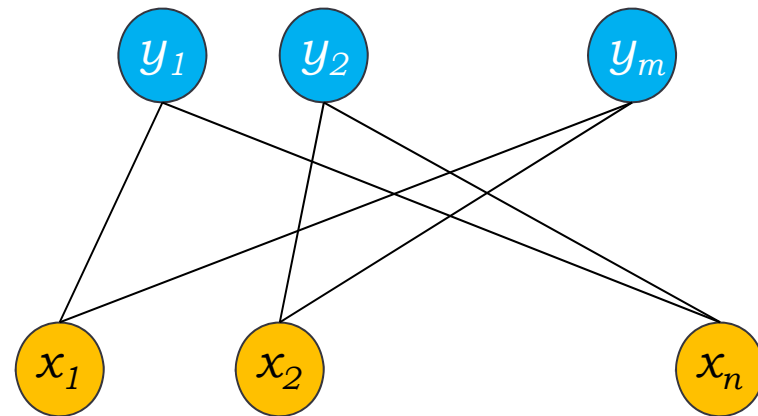
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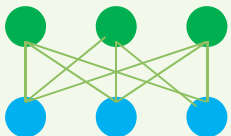


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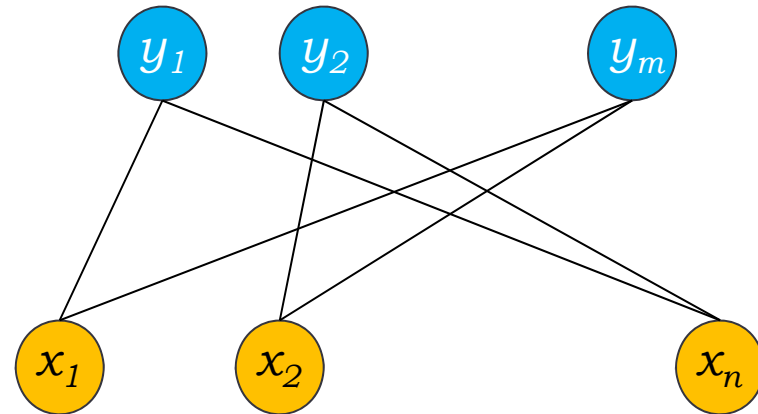


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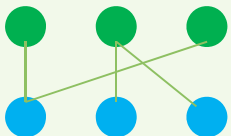


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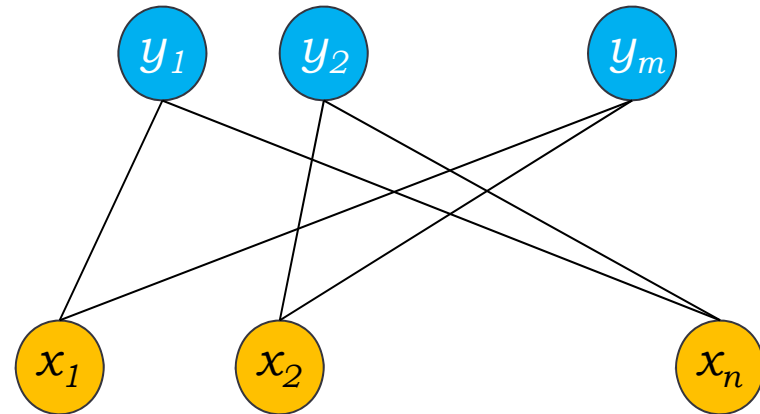


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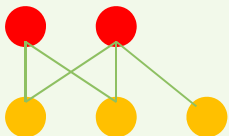


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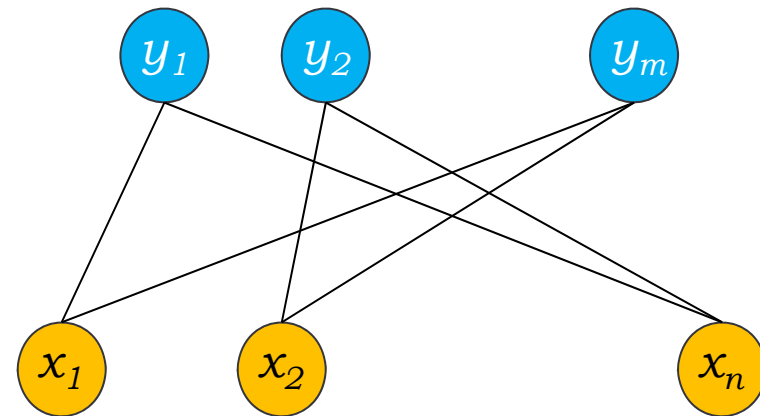


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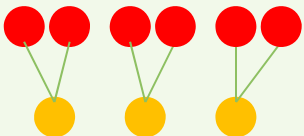


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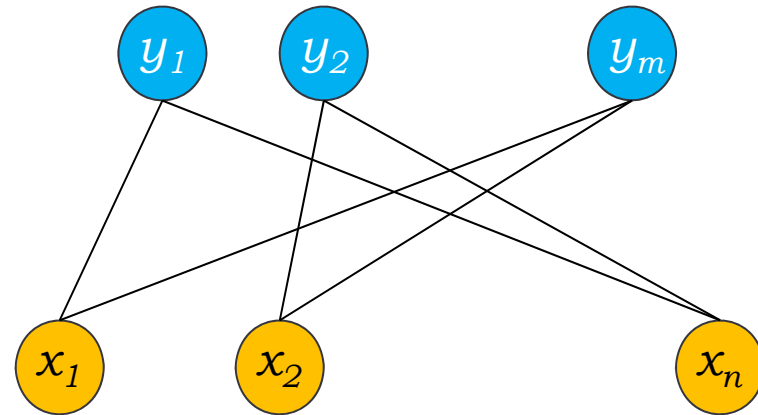


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- ⊙ A bipartite graph with n *pattern nodes* and m *constraint nodes*.
 - ⊙ Nodes represent neurons.
 - ⊙ Link weights are 0 or 1.
- ⊙ Broadcast system.
- ⊙ *Sparse and expander.*
- ⊙ Non-binary neurons
 - ⊙ Output of a node is the firing rate of the neuron.



HOW IT WORKS

1. Initialization
2. Iterative update
3. Convergence

- ③ Iterative update of nodes states according to some update rule.

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- ⊙ The structure is the same as LDPC parity check matrices except for:
 - ⊙ Real field operations.
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- ⊙ The structure is similar to a *hetero-associative* memory.

- ⊙ State of each node = short term firing rate of neurons.

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- ⊙ For the moment, we assume H is given and only address the neural update rule.

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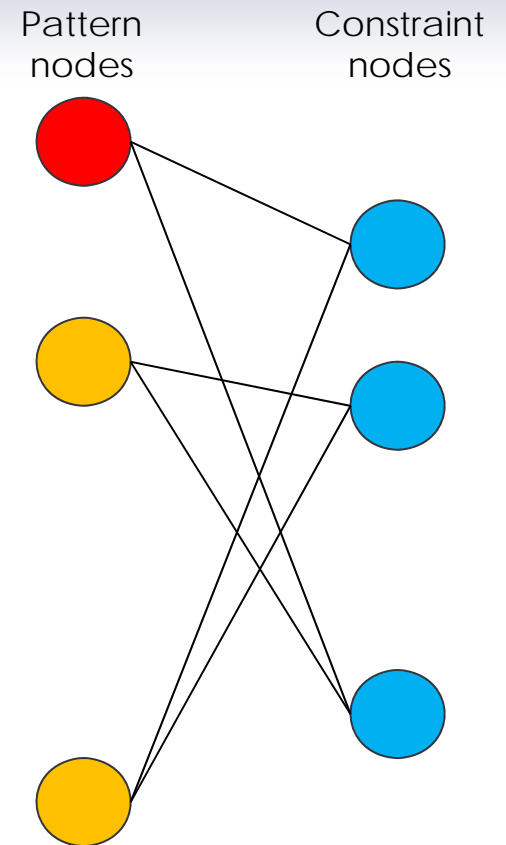
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Stability



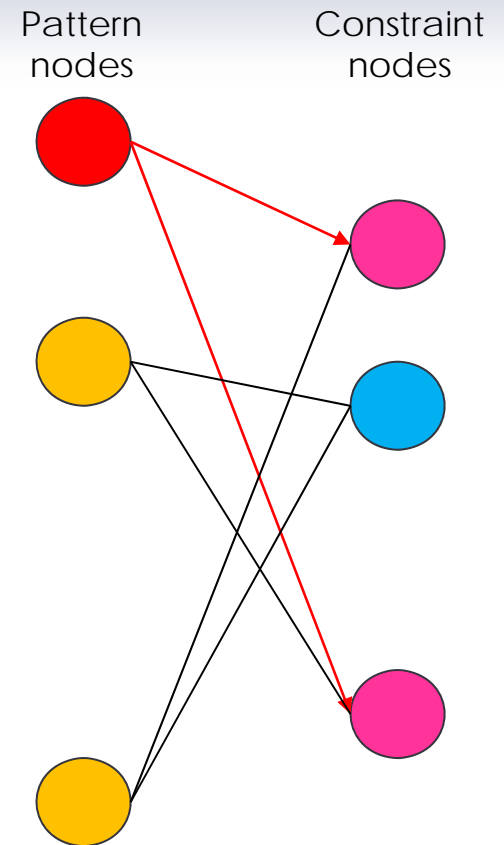
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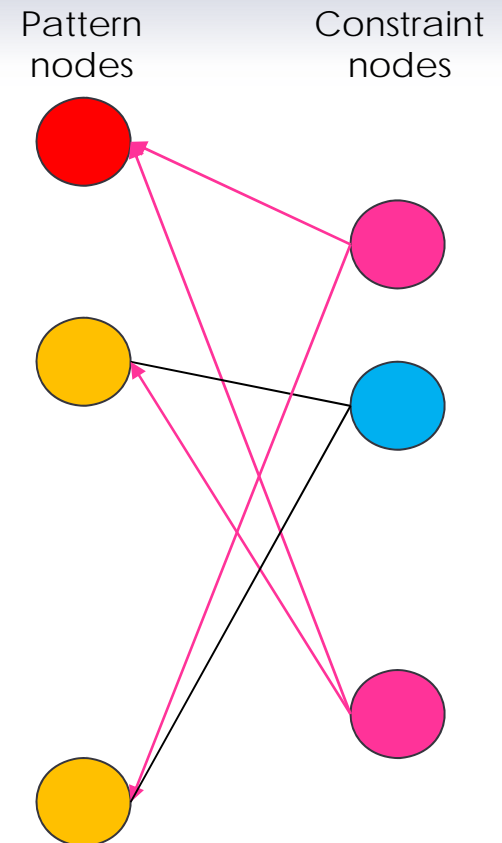
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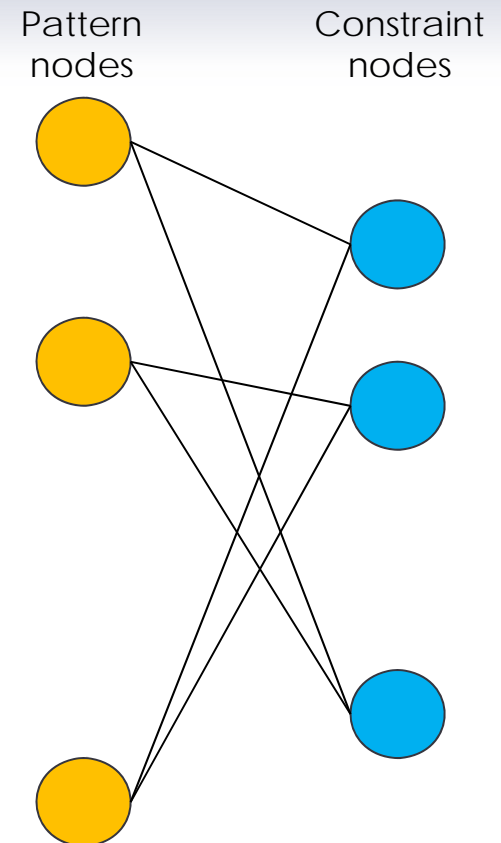
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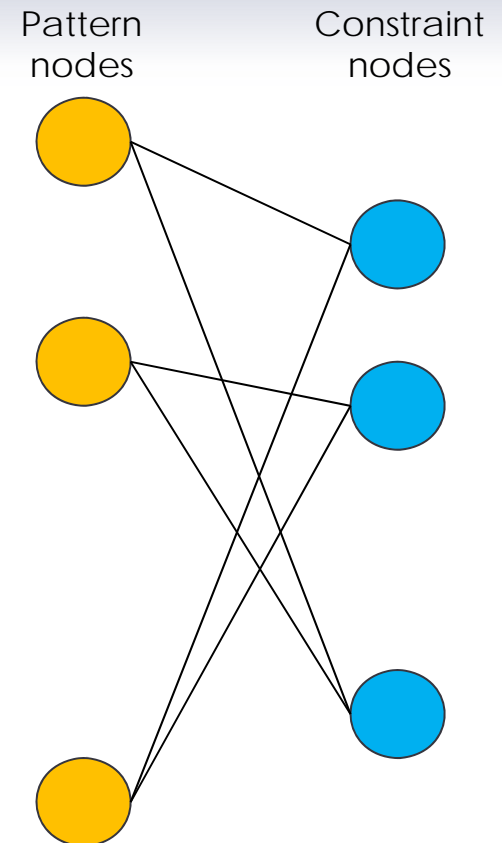
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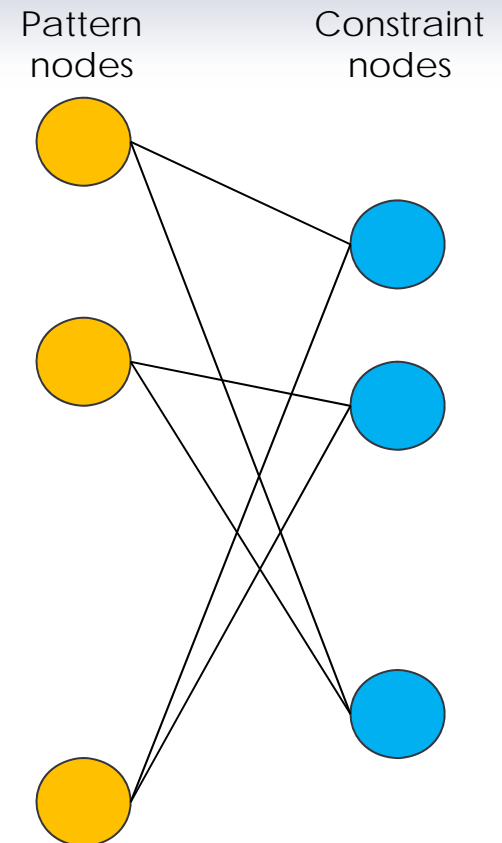


Noise tolerance



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Solution
Similar in nature to Sipser & Spielman's expander codes.

Noise tolerance ✓

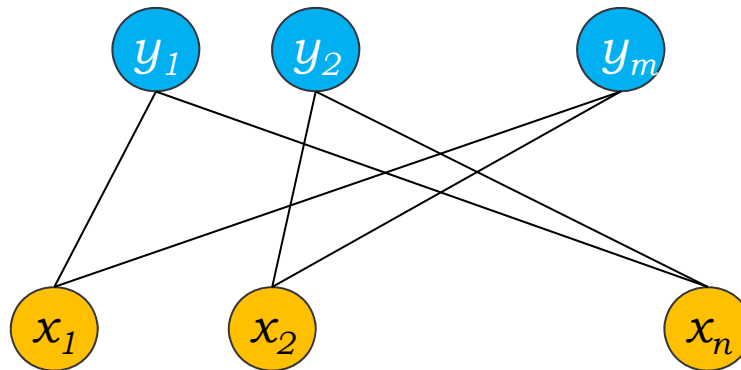
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H : $m \times n$ 0/1 matrix.

x : $n \times 1$ integer vector.

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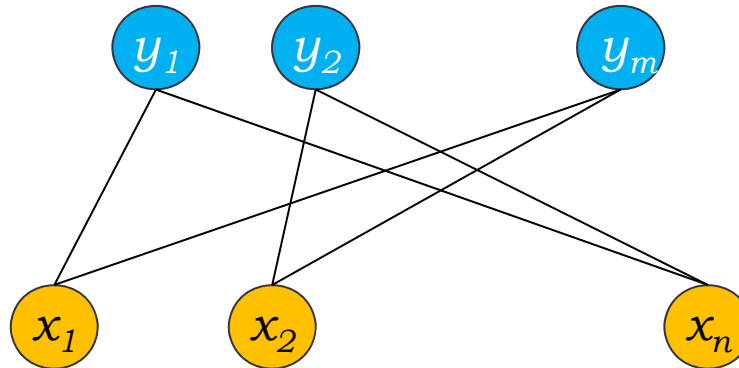
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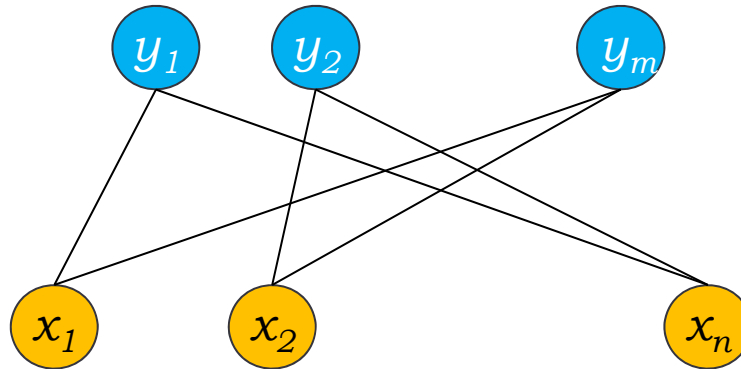
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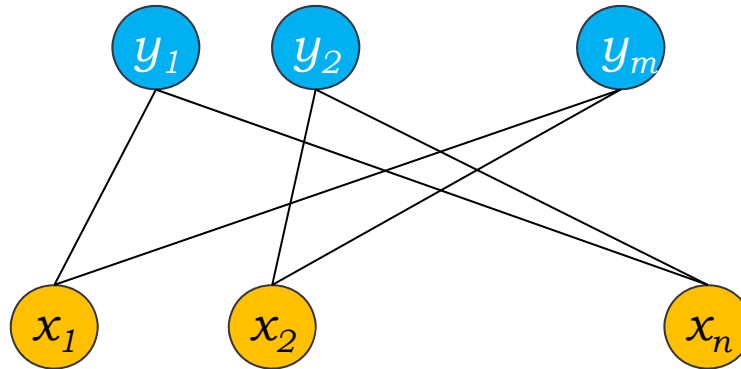
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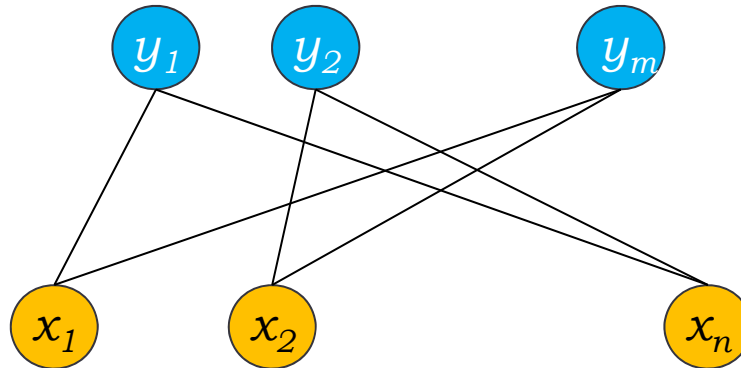
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- ◎ Winner-take-all
- ◎ Bit-flip

THE ALGORITHM: DETAILS (CONTD.)

Solution

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$$Hx^\mu = b$$

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- ⊙ Noise free case: If x^μ is given, no constraint node fires.

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- ⊙ If $x^\mu + \text{noise}$ is given:

$$g_j = \frac{\sum_{i=1}^m H_{ij} y_i}{d_p}$$

- ⊙ g_j is larger for corrupted nodes.
- ⊙ If the graph is expander, the update will reduce noise.
- ⊙ Firing rates are saturated to make this happen.

RESULTS

- ⊙ The pattern retrieval capacity:

$$S^n / (d_c S)^m$$

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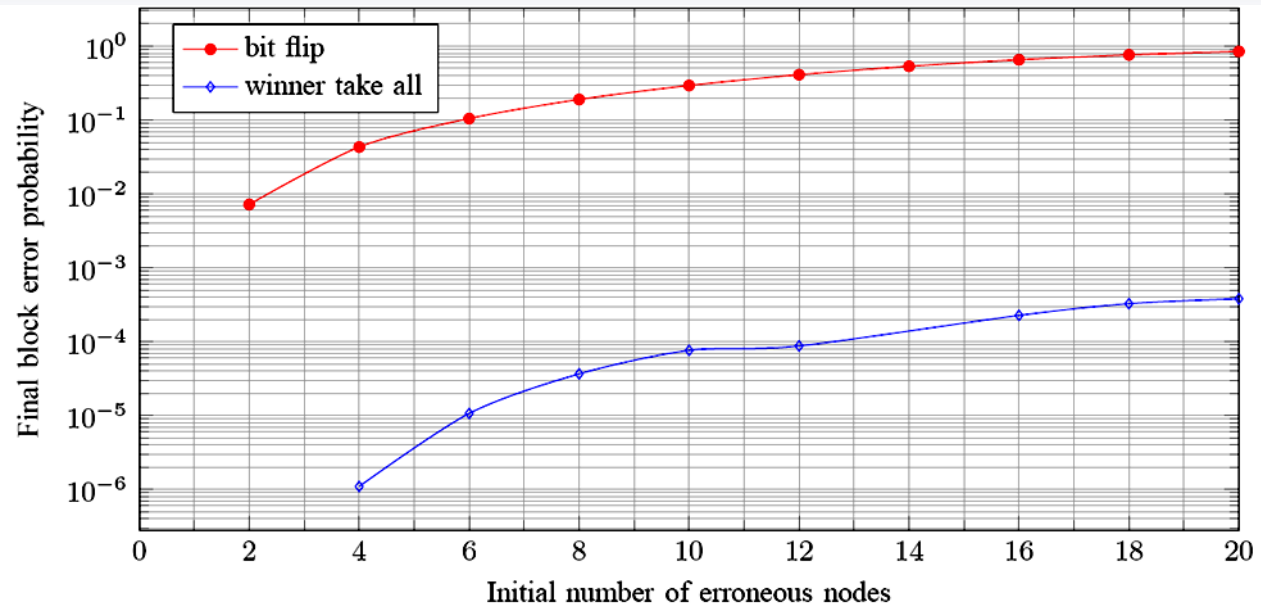
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- ⊙ **Theorem:** If H is an expander graph, the *winner-take-all* and *bit-flipping*^{*} algorithms are guaranteed to correct two erroneous nodes.

RESULTS (CONTD.)

◎ For more than two errors:



◎ $n = 600, m = 300, d_c = 10, d_p = 5$

◎ Noise model: integer values in $[-5, 5]$



ONGOING WORK

WHAT HAPPENS TO H?

- ⊙ So far, H was assumed to be given.
- ⊙ In order to find H, there are two possible approaches:

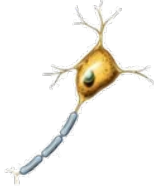
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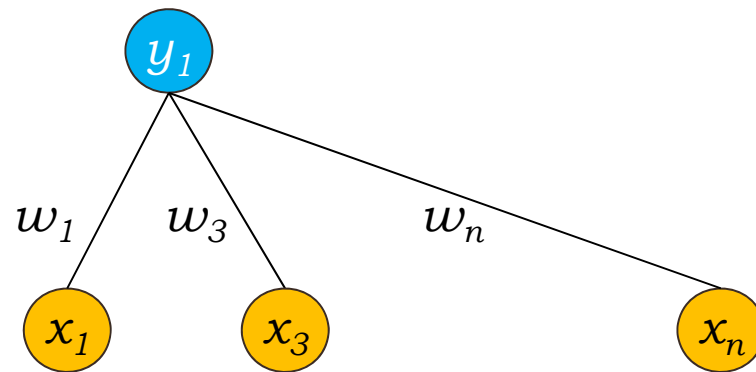
- ◎ So far, H was assumed to be given.
- ◎ In order to find H , there are two possible approaches:
 1. Infer H from data
 -  Back propagation does not work: H is not guaranteed to be an expander.
 - Low activity assumption might help us here.
 - If data is sparse itself, we might be able to use a similar structure to learn from data



WORK IN PROGRESS

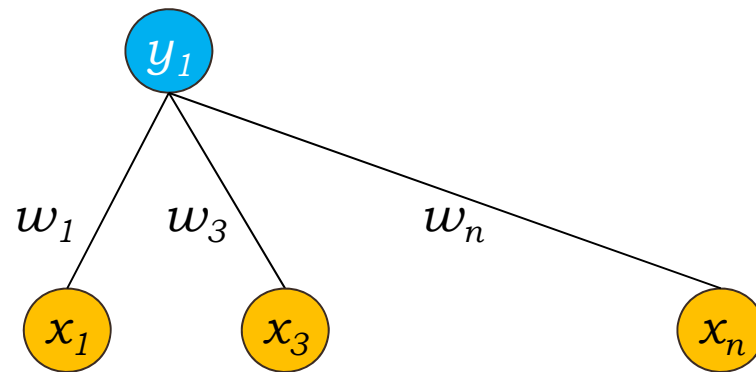
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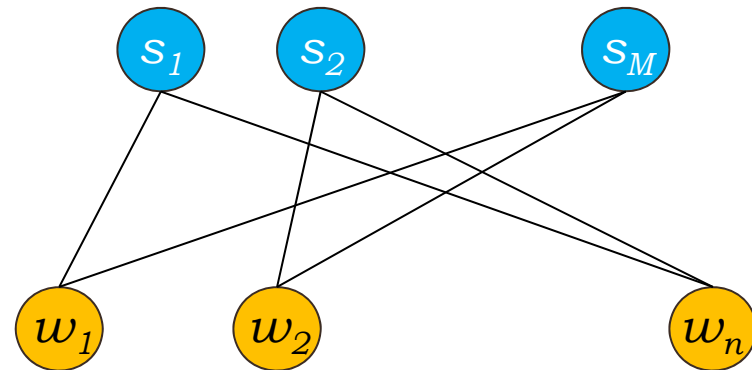
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- ⊙ If the weights are correct, y_1 will be zero for all patterns.
- ⊙ If not, let of s_μ be the output of y_1 for pattern μ .

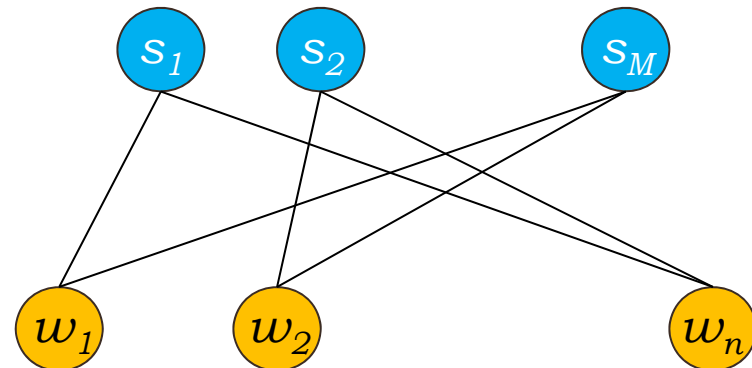
INFERRING H FROM DATA (CONT'D.)

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INFERRING H FROM DATA (CONT'D.)

- ⊙ Consider the following structure:
 - ⊙ Link weights are patterns.
- ⊙ If w_1, \dots, w_n are correct, s_1, \dots, s_M will all be zero.
- ⊙ If not, we have the same problem as before.

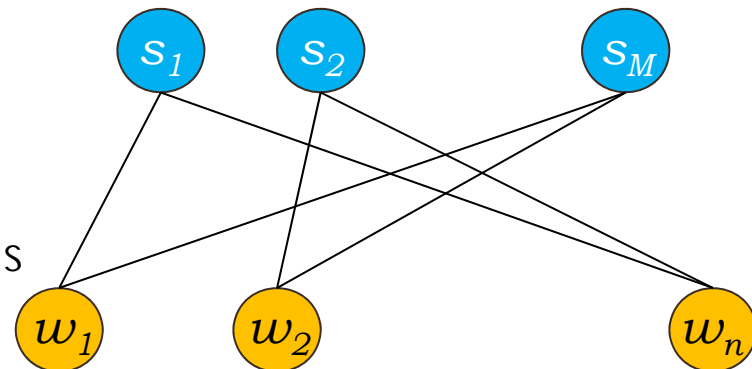


INFERRING H FROM DATA (CONTD.)

- ⊙ Consider the following structure:
 - ⊙ Link weights are patterns.
 - ⊙ If w_1, \dots, w_n are correct, s_1, \dots, s_M will all be zero.
 - ⊙ If not, we have the same problem as before.

- ⊙ If we have low activity patterns, this graph is also sparse!

- ⊙ We might apply the previous algorithm for the learning phase as well!



WHAT HAPPENS TO H ? (CONT'D.)

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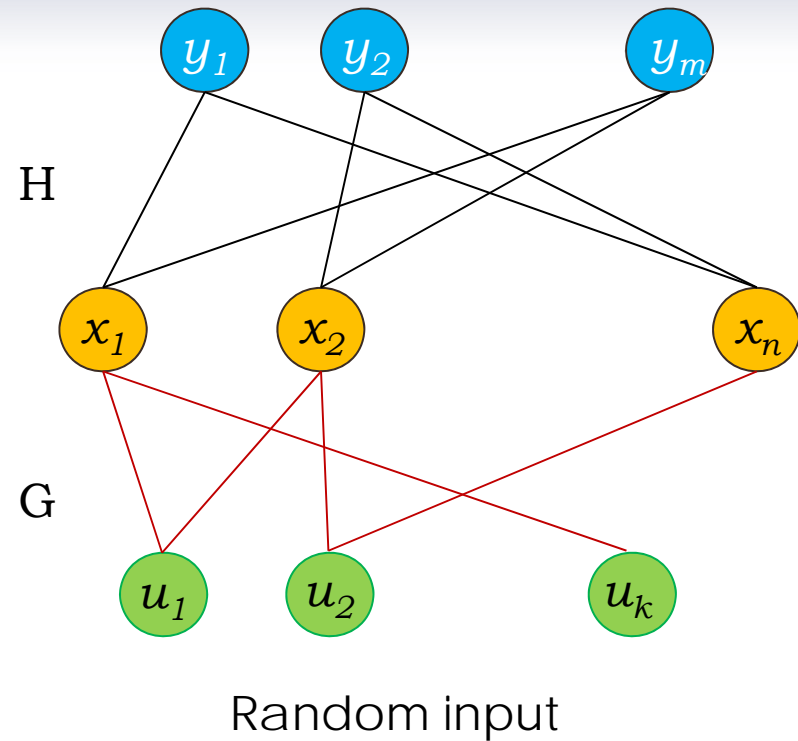


- This corresponds to pre-processing stages in the brain.

- ◎ For the second approach, noise model must be modified.

WHAT HAPPENS TO H? (CONT'D.)

- ① u_1, \dots, u_k can be purely random.
- ① $Gu^\mu = x^\mu$
- ① $HG = 0$
- ① G Should be sparse as well.



CONCLUSIONS AND FINAL REMARKS

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- ⊙ An associative memory with exponential capacity is proposed.
 - ⊙ All that is needed is a two-layer neural network which is also an expander.
 - ⊙ Simple update rules
- ⊙ We are now working on:
 - ⊙ Inferring H from data or
 - ⊙ Mapping input to a higher dimension.

THANKS FOR YOUR ATTENTION

Any
Questions?

